The blessing and the curse of the big image

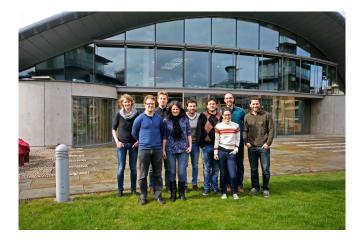
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Cambridge Centre for Analysis

Cambridge Image Analysis (CIA)



1 PI, 3 PostDocs, 6 PhD students, 3 Masters students www.damtp.cam.ac.uk/research/cia/ www.images.group.cam.ac.uk

The blessing

Images are <i>big</i>	
HD video	6 MB/image uncompressed 180MB/second
Digital cameras	80-200 million pixels 480-1,200MB/image
MRI	16 MB/volume at 1mm ³ 590MB/volume at 0.3mm ³

High number of dimensions:

- 2D–3D astronomical imaging, global terrestrial seismic tomography, arts applications (Fitzwilliam Museum)
- 3D dynamic microscopy (CAIC)
- 3D-4D (dynamic) MRI (MRRC), PET/SPECT (WBIC)
- 5D Diffusion MRI



Image credit: Wikimedia/Selbymay



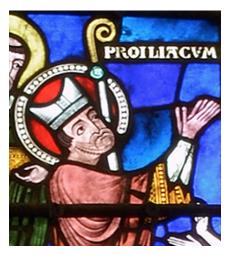


Image credit: Wikimedia/Selbymay

The curse

Images are *redundant*





Challenges

1 How to extract the interesting information?

- classification, image labelling, segmentation, sparse representation, image parametrisation
- methods from machine learning, statistics

Dynamic image analysis for light microscopy

Optical flow estimation:

Cell tracking:

Computations by Hendrik Dirks/CIA, image data from Goldstein Lab

References: Möller et al. '12; ...; cell tracking through mitosis with Burger, Grah, Reichelt (CRUK CI)

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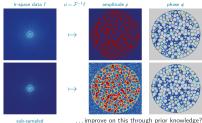
2 How to deal with incomplete data?

- only limited measurements available, or
- deliberate reduction for speeding up the imaging process
- methods from statistics, inverse problems, partial differential equations, variational methods, regularisation, large-scale optimisation

Image reconstruction from phase-encoded MR data



Phase difference $\phi_1 - \phi_2$ of two images u_1 and u_2 proportional to velocity of a fluid along a gradient.



... improve on this through prior knowledge?

References: Gladden et al. '90-; ...; Benning, Gladden, Holland, CBS, Valkonen, Journal Magnetic Resonance '13. Animations courtesy of Alex Tayler.

Mathematical framework

The problem

Given data f, find the image information u that solves

f = T(u) + n

where T models the relation between u and f, and n is noise.

Issues

In most real-world applications, reconstructing f from u is

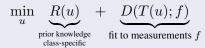
- not unique (T "forgets" data), or
- **not stable** (small variations in $f \rightarrow$ large variations in u),
- **\blacksquare** not clear, because the noise *n* is unknown

We need additional prior knowledge on u...

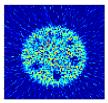
Mathematical framework

Energy minimisation framework

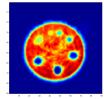
Reconstruct image information u from data f by minimising



- \rightarrow state of the art optimisation for large-scale computing
 - convex optimisation, operator splitting
 - subspace decomposition, parallelisation, GPU computing



naive PET reconstruction



result of energy minimisation



Figure: Adoration of the Shepherds, Sebastiano Del Piombo (1519)



Figure: Detail



Figure: Small damages restored with structure inpainting



Figure: Large damages restored with structure & texture inpainting

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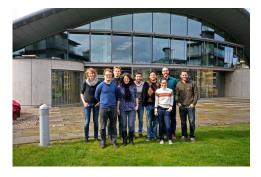
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Sponsored by EPSRC, Isaac Newton Trust, LMS, Mathworks, The Royal Society, Leverhulme Trust, and Wellcome Trust.